

## ERW Seam Weld Inspection with AutoTrack

The **ERW Seam Weld Inspection with AutoTrack** provides automated, semi-automated or manual control over the ultrasonic inspection process of the straight seam weld on ERW pipes. This compact stand-alone system is easily integrated into your existing inspection processes.

**AutoTrack** is NDT's inc. proprietary solution for real-time tracking of deviations in the location of the longitudinal seam weld and continuously aligns the inspection probes over the seam weld.

The system uses reliable, accurate and proven technologies based on NDT Inc's 30 years of experience designing and installing inspection solutions for industrial ERW pipe manufacturers.



System Components	Basics of System Operation
(1) Probe Block & UT Probes	1. Seam weld on ERW pipe is placed at test position (12 o'clock).
(2) Probe Carrier	2. <b>Smart Camera (3)</b> is configured and aligned so the seam weld reference line is visible in camera's field of view.
(3) Smart Camera	3. <b>AutoTrack</b> scans the pipe surface to identify the location of weld seam reference line.
(4) Arched Guide Rail	4. <b>AutoTrack</b> image processing routine will continuously track the weld seam reference line during the inspection process.
(5) Servo Motor Drive	5. <b>AutoTrack</b> sends a digital signal to the PLC when the reference line moves or devi- ates from its initial position.
(6) PLC & Inter-Communica- tion Hub (not shown)	6. Inter-Communication Hub controls the Servo Motor (5) to move the Probe Carrier (2) on the Arched Guide Rail (4) to align the Probes (1) over the seam weld.

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## Reliable, accurate and proven technologies

Operating Characteristics	Software Characteristics
<ul> <li>Accommodates all types of ERW pipes.</li> <li>Compatible with all pipe surface finishes.</li> <li>Accommodates all pipe diameters &amp; UT probes.</li> <li>Designed for industrial manufacturing.</li> <li>Opvironments with an IP 67 rated Smart campra</li> </ul>	<ul> <li>Real-time image processing of 45 FPS.</li> <li>Electronically controlled variable focus camera lens for easy setup.</li> <li>Software and image processing routines run in Smart camera – no PC required.</li> </ul>
<ul> <li>Inter-Communication Hub provides interfaces for 2 joysticks, PLC, servo motor and Smart camera.</li> <li>Ethernet connectionfor real-time camera image display and data storage.</li> </ul>	<ul> <li>Configurable camera &amp; tracking parameters.</li> <li>Storage/retrieval of AutoTrack setups, eliminating pipe change over delays.</li> <li>Multiple operating modes.</li> </ul>

Parameters & Operating Modes					
Camera parameters <sup>1</sup>	Exposure, gain and focus	Digital values used to maximize the quality of images captured by the camera.			
Tracking parameters <sup>1,2</sup>	Threshold par Minimum inte seam weld re Region of Inte parameters - Area between scanned by Au Purple Line - weld reference by AutoTrack Tracking Zone Area between lines.	rameter - ensity of the ference line. restXLeft, XRight hyellow lines utoTrack. Axis of seam be line detected e -Center Offset h dotted green			
Operating Modes	Manual Mode Automatic	Operator uses a joystick to manually control position of the probe holder. AutoTrackis active, tracking the reference line (purple line) and keeping			
	Mode	it in the Tracking Zone with the controlled servo motor which moves the probe holder.			
	Semi-Automatic Mode	AutoTrack is active. The operator can also use the joystick to override AutoTrack and manually position the probe holder.			

(1) Multiple setups of camera and tracking parameters can be defined and recalled to accommodate di erent pipe diameters and pipe surface finishes.

(2) PC viewer program is available for real-time display of camera images and tracking lines.